



Race Master System User Guide

EMC Conformance

All Raymarine equipment is designed to the best industry standards for use in the recreational marine environment. The design and manufacture of Raymarine equipment conforms to the appropriate Electromagnetic Compatibility (EMC) standards. Correct installation is required to ensure that performance is not compromised.



Important

Due to the wireless communication systems used in Micronet instruments they are only recommended for use on boats up to 18 metres (60 ft.) **Before installing to a boat of aluminium or steel construction, please contact your Raymarine dealer.**

Like any other electronic instruments your Micronet system is designed to serve only as an aid to navigation and it remains the skippers responsibility to maintain a permanent watch and be aware of developing situations.

Any attempt to take a Micronet product apart will invalidate the warranty. The battery may only be replaced by a person trained and approved for this purpose.

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1 Introduction

Key Features

Your Micronet Race Master System provides a unique combination of features:

Viewable from both sides of the boat

Two LCD displays mounted at an angle to permit viewing from either side of the boat.

Solar Power

The Micronet Race Master System is powered for life by the environment. Although feature packed and highly visible in all conditions, current demand is so low, and the supply so efficient, that the solar-powered display is self sufficient.

Integrated Heading Sensor

With it's integrated fluxgate compass, the Micronet Race Master acts as a powerful racing compass; with functions for capturing the mean wind direction, wind shifts and the starting line bias.

Networked Speed and Depth

Using the networked Hull Transmitter with the depth and speed transducers, the Micronet Race Master System becomes a complete navigational and race information system.

Bar Graph display

Both screens of the Micronet Race Master incorporate a bar graph to permit analogue display of Wind Shift, Speed Trim or Depth.

Networked Data capability

By connecting additional Micronet transmitters (e.g. Wind Transmitter) or NMEA devices, the Micronet Race Master can display a wide range of navigational data.

Remote Control capability

By purchasing an optional Raymarine Remote Display, you can control your Race Master from any location in the boat.



2. Basic Operation



Important: Ensure that the "Auto Network" procedure described on the yellow instruction sheet and full Setup and Calibration has been performed correctly before attempting to use your Micronet Racemaster System.

2.1 Display Information



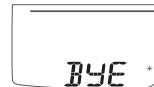
2.2 Switching the System On and Off

To switch your Micronet Racemaster System on or off press  for 2 seconds.

Switch on



Switch off



2.3 Power Management and Battery Life

What makes your Micronet Race Master System possible is Raymarine's revolutionary approach to power management. By reducing the amount of power being used by the electronics and maximizing the potential of the sun to provide power, the Micronet Race Master System is capable of virtually perpetual operation.

Power status is indicated by two icons on the display:

Battery Level  and  Charge Rate

Used together these icons will show the condition of the power supply.

If using the displays at night, power usage can be reduced dramatically by switching the Backlighting to level 1. If Backlighting is not required on displays located below decks it is best to set them to "Local" Backlighting control (see page 25) so that power is not being wasted in displays which may not be visible from the one being viewed.

Bright Sunny Day 	 	Battery is charged and being topped up by the sun. (see Note)
	 	Battery is low and being charged by the sun.
Overcast Day 	 	Battery is charged and requires no further charging.
	 	Battery is low but maintaining it's level.
Night 	 	Battery is charged but is not charging.
	 	Battery is low with no charging.
LOW Power	 	It is recommended that the instrument be left in daylight for some time for the battery to recover. A fully discharged battery will recharge in approximately 12 hours of direct bright sunlight.

Note: If the internal battery is fully charged then it does not matter how much the display is subjected to bright sunlight, no further charging is required and the Charge Rate Indicator will remain low.

If the display is to be stored for a long period before next use (e.g over winter), ensure that the battery is fully charged before storage.



Warning: Artificial light WILL NOT recharge the battery. Placing your Race Master close to an artificial light will seriously damage the display. Only recharge in natural daylight.

2.4 Sleep Mode

If there is no boat speed or change in heading registered on the system for a period of 12 hours your Micronet Race Master will switch off to conserve power. A "POWER SAVE" alarm will sound before the system switches off. Pressing any button within 10 seconds of the alarm sounding will allow the system to remain switched on.

2.5 Backlighting

At any stage of the display's operation, press and hold  for 2 seconds to access the lighting control.

Pressing  and  will scroll through the options OFF, 1, 2 and 3 whilst changing the backlighting.

Depending on the display setup (see page 25), backlighting on the whole system or just the single display will be altered.

Backlighting is automatically switched off in daylight as part of the display's power saving feature and will not operate in daylight.

2.6 Keylock

The Keylock feature protects from accidental key presses. Keylock can be enabled or disabled in setup (see page 24), it is disabled by default.

When keylock is enabled, pressing a key causes the unit to give the unlock key prompt. Press  followed by  to unlock the keys (the keys will function for one minute, after which the keys will automatically relock).

2.7 Audible Signals and Alarms

At stages during its operation your Micronet Race Master will beep to indicate alarms or moments of importance.

Power-up The display will issue a single beep as it is switched on.

Button Press A single beep is issued each time a button is pressed. A second beep is issued when a button has been held down for two seconds.

Timer A single beep will be issued at each minute of the countdown.

With 1 minute left to go a beep will sound every 10 seconds.

With 10 seconds to go a beep will sound every second.

Countdown complete will be indicated by a single burst of three beeps.

Alarm Continuous bursts of three beeps will indicate an alarm.

The alarm activated will be indicated on the display. Pressing any button will clear the alarm (See fault finding section on page 32).

2.8 Safety and Disposal

Your Race Master contains Manganese Lithium Dioxide batteries which should be disposed of correctly. Do not dispose of any instrument in domestic waste. Refer to regulations in force in your country.

If in doubt return the instrument to Raymarine. for correct disposal.

3 Racing Functions of the Race Master System

3.1 Some definitions and terminology

True Wind Direction (TWD), the current actual direction of the wind over the water, expressed as a compass heading. If the boat is head to wind, the TWD is the same as the heading of the boat.

Mean Wind Direction (MWD), the average of the True Wind Direction (TWD) over a sufficiently long period to even out any regular periodic changes in the wind direction.

Tack Angle (TAK), the angle through which the boat turns when going from close hauled on one tack to close hauled on the other. Typically this is about 90 degrees.

Line Bias, the angle between the heading of the start line and a line at right angles to the wind.

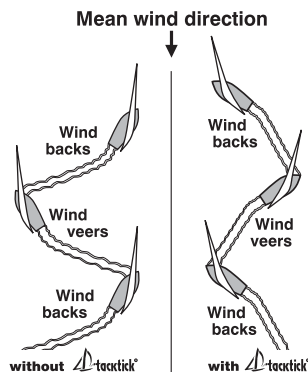
3.2 Improving Race Performance with the Race Master Racing and Wind Shifts

Like most things in sailing, the wind does not remain constant in either strength or direction.

The crew tend to react naturally to gusts but find wind shifts more difficult to detect. However the wind does tend to shift in regular patterns, oscillating from one side of the Mean Wind Direction (MWD) to the other. Every shift in the wind requires the boat to alter its heading in order to maintain a close hauled course. A shift that allows the boat to change its heading closer to the Mean Wind Direction (MWD) is called a “lift”; a shift that forces the boat to change course away from the Mean Wind Direction (MWD) is known as a “header”.

In an oscillating wind, a boat that regularly tacks when headed will spend more of its time sailing a lifted course and will sail a shorter distance to the windward mark than a boat that regularly sails a headed course. This gives the boat sailing in the lifts a considerable advantage.

In the diagram, the boat on the right sails a shorter course by tacking when headed and thereby sailing mostly in lifts.



The opposite is true sailing down wind. A boat that gybes to sail in the “headers” will sail a shorter course to the leeward mark than a boat that sails a “lifted” course.

Optimise wind shifts

Your Micronet Race Master is the ultimate wind shift indicator, giving you precise, clear numerical and graphical readouts.

During the race, you can get an instant visual display of:

Your heading as a large stable digital number (the upper display)

How far you are sailing above or below the mean close hauled heading (lifted or headed) as a precise digital number (the lower display)

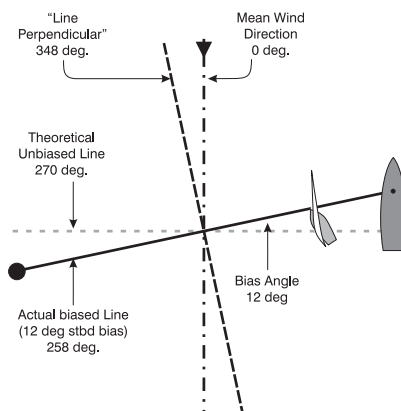
How far you are lifted or headed in bar graph format for instant visual impact (the vertical bar graph)

Micronet Race Master gives you this critical information when you are sailing both upwind AND downwind. You sail your boat for maximum speed to windward, using the Micronet Race Master to identify the headers and lifts to help you decide when to tack. Timing your tacks and gybes is absolutely critical to winning races and Micronet Race Master shows you the wind shifts more clearly than ever before.

Racing and Start Line Bias

If the starting line is laid at exactly right angles to the wind, the distance sailed to the windward mark is the same wherever the boat starts on the start line.

If the start line is not laid at exactly ninety degrees to the wind, there is a favoured end to the line; a boat that starts at the favoured end starts upwind and therefore ahead of a boat starting at the other end of the line. The angle between the actual line heading and the theoretical line at right angles to the wind is called the Line Bias; the larger the bias angle, the greater the advantage to be gained from starting at the favoured end of the line.



The diagram (right) shows the relationship between these values.

Optimise your start with the Micronet Race Master

Your Micronet Race Master has the ability to capture the Line Perpendicular (the heading at right angles to windward of the start line) and to display the Line Bias angle and the favoured end of the line.

3.3 Before the Race

If you have wind data available on the Micronet Network, the required information is automatically captured by the system (see section 5.7); otherwise you need to programme the Mean Wind Direction (MWD) and Tack Angle (TAK) as follows:

To set the Mean Wind Direction (MWD) and Tack Angle (TAK) in "Single Button" mode

Go to the Wind Shift (WND) page.

Sail upwind for several minutes to determine your average close hauled heading on each tack.

Press and hold . Rotating lines will appear on the display.

Steer your average close hauled course on either tack.

When the display shows the pop-up "TAC NOW", tack the boat and sail your close hauled course on the other tack.

The rotating lines will reappear on the display, hold your close hauled course until the Tack Angle (TAK) pop-up appears.

The displayed value can be adjusted using  and .



To capture the Line Perpendicular and the Line Bias

Ensure that the Mean Wind Direction (MWD) has been captured (see the section above).

Go to the Line Bias (LiNE) page.

Sail directly along the start line, then press .

A pop-up is displayed showing the Line Bias angle and the favoured end of the start line based on the captured Mean Wind Direction (MWD).

When the pop-up closes, the bottom pane shows the Line Perpendicular (the bearing at right angles to windward of the the start line).

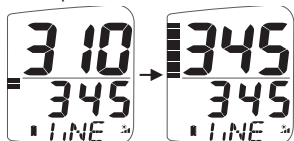


To check the direction of the Line Bias

If the wind changes prior to the start, provided you have captured the Line Perpendicular, as described above, you can check the Line Bias at any time as follows:

Go to the Line Bias (LiNE) page.

Steer the boat towards the eye of the wind until the Heading in the upper pane matches the Line Perpendicular in the lower pane.



If the wind is coming from the starboard side, the line is starboard biased. If the wind is coming from the port side, the line is port biased.

To set the Start Timer

Go to the Race Timer (TMR) page.

Press for 1 second, the last start countdown value is shown, flashing.

If required adjust the countdown value using and .

Press to exit edit mode and prepare for countdown.

At the first "gun" press to start the countdown.

The timer will sound a single beep at the end of each minute.

During the last minute, the timer will sound a beep every ten seconds.

During the final ten seconds, the timer will beep every second.

"START" will be indicated by a triple beep.

At the end of the countdown, a pre-selected data page is displayed, (see page 25 to select the page).

The timer will count the elapsed time in the background, until stopped by scrolling to the Race Timer (TMR) page and pressing for two seconds.

To adjust the Timer

At any time during the countdown, press to resynchronise the countdown to the nearest minute.



Press and hold for 1 second to enter timer setup



Select the desired countdown time



Press and hold for 1 second to store the countdown time



Ready to start countdown



Press to start



Countdown time in progress



Press to re-synchronise to nearest full minute (8:00)

3.4 During the Race

Sailing upwind.

Tack when headed to keep the boat sailing on the lifted tack.

The bar graph indicates the Wind Shift in 2.5 degree steps from a central zero. Bar Graph above the centre line indicates a lift, Bar Graph below the centre line indicates a header.

When the Wind Shift (WND) page is selected, Wind Shift is shown as a + (lifted) or - (headed) value in the lower pane.



Oscillating wind pattern



If the wind is swinging regularly either side of the Mean Wind Direction (MWD), you should tack on headers to keep sailing on the lifted tack, i.e. you should tack on "-" digital or bar graph indications.

Permanent wind shifts

These can be recognised as a constant header on one tack, and a constant lift on the other tack. In this situation, you can adjust the Mean Wind Direction (MWD) as follows:

If you have Wind Data on the Micronet Network:

1. Go to the Wind Shift (WND) page
2. Press , Mean Wind Direction (MWD) is reset to the current True Wind Direction (TWD).
3. The Mean Wind (MWD) pop-up is displayed.
4. If required, the value may be adjusted using  and .

If you do not have wind data on the network:

1. Sail close hauled on either tack.
2. If on starboard tack, press . If on port tack tack, press . The new Mean Wind Direction (MWD) is captured.
3. The Mean Wind Direction (MWD) pop-up is displayed.
4. If required, the value can be adjusted using  and .



Sailing Downwind



Gybe to keep the bar graph low, to sail on the headed tack.

The bar graph displays Downwind Angle (the angle of the boat from the mean downwind direction) in 2.5 degree steps from 0 to 50 degrees, from zero at the bottom of the display. For example, at 45 degrees the bar graph is almost full length and the boat is sailing at 45 degrees from the mean downwind direction.

When the Wind Shift (WND) page is selected, Downwind Angle is shown on the numeric display and the direction is shown by  (Port) or  (Stbd), e.g. the example shows that the boat is sailing 20 degrees to starboard of the mean down wind direction.

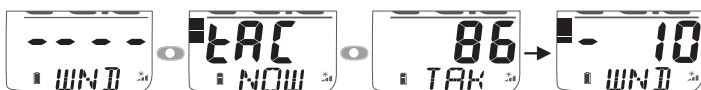
4 Advanced Racing Functions

The following additional functions are provided to set Mean Wind Direction (MWD) and Tack Angle (**Note**: they are not required if wind data is available on the Micronet network).

To set the Mean Wind Direction (MWD) and Tack Angle(TAK) by sailing closehauled

1. Go to the Wind Shift (WND) page.
2. Sail upwind for several minutes to determine your average close hauled heading on each tack.
3. Steer your average close hauled heading on either tack.
4. Press  the display will beep twice and "TAC NOW" will show for two seconds.
5. Tack and sail your average close hauled heading on the new tack.
6. Press  again, the display will beep three times and the Tack Angle (TAK) pop-up will be displayed.

The Tack Angle (TAK) can be adjusted using  and .



To set the Mean Wind Direction (MWD) to a known value

If you know the required Mean Wind Direction (MWD), you can set it at any time as follows (you do not need to be sailing):

1. Go to the Wind Shift (WND) page.
2. Press and hold  for 2 seconds, rotating lines are shown.
3. Press , the Mean Wind Direction (MWD) pop-up is displayed.
4. Set the desired heading using  and .



To set the Tack Angle (TAK) to a known value

If you know the required Tack Angle (TAK), you can set it at any time as follows (you do not need to be sailing):

1. Follow the procedure above to display the Mean Wind Direction (MWD) pop-up.
2. Press , the Tack Angle (TAK) pop-up is displayed.
3. Set the required value using  and .

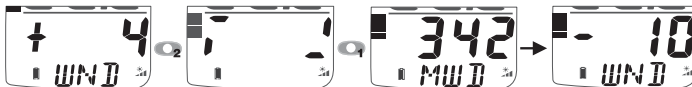


To correct the Mean Wind Direction (MWD) by going head to wind

For Wind Shift to work correctly, you must ensure that the tack angle is captured using one of the methods described above.

1. Go to the Wind Shift (WND) page.
2. Take the boat head to wind.
3. Press and hold  for 2 seconds, rotating lines are shown.
4. Press and hold  again for 1 second, the Mean Wind Direction (MWD) pop-up is displayed.

If necessary, adjust the captured value using  and .



5 Micronet Functions

Information in the bottom pane is displayed in a Chapter and Page format, each chapter containing one or more pages of related information.

When Speed, and Depth transducers are connected via the Hull Transmitter, the following chapters and pages are available:

Wind Shift

Heading

Speed, Maximum Speed, Speed Trim, Distance Travelled, Trip Distance, Sea Temperature

Depth, Depth Pop-up, Depth Shallow Alarm

Note: Data from additional Micronet transmitters and from connected NMEA devices can also be displayed on the Micronet Race Master.

The diagram on page 15 shows the full set of data displays that are available.

For a detailed description of individual data items supported on the Micronet network, see the Micronet Data user guide on your product CD or on the Raymarine web site.

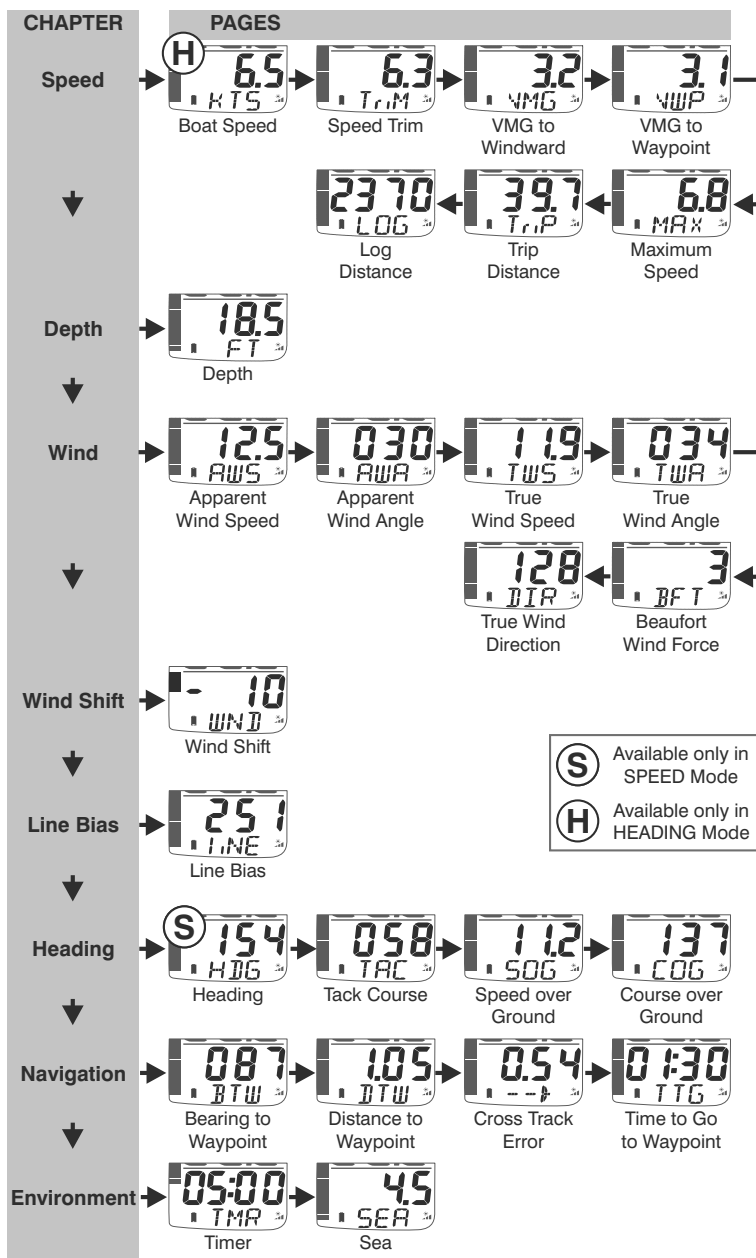
5.1 Chapter and Page operation

Use  to scroll through the chapters and  and  to move between the pages within a chapter.

Pressing  at any time moves to the next chapter and the page last selected in that chapter will be displayed. Both chapter and page selection will scroll back to the first page once a cycle has been completed.

When switched on, the Race Master automatically detects the transmitters connected to the Micronet network and selects Networked or Standalone mode as appropriate. Pages for which no data is available on the network are automatically removed from the page rollover.

Chapter and Page Diagram



5.2 Display Modes

Three display modes can be selected in setup (page 24).

Heading Mode (default)



The top pane of the display always shows the boat's Heading and the heading page is removed from the bottom pane rollover.

The bar graph can be configured to show either **Wind Shift** (default), Depth or Speed Trim (see below).

Speed Mode



The top pane of the display always shows Boat Speed and the Boat Speed page is removed from the bottom pane rollover.

The bar graph can be configured to show **Speed Trim** (default), Depth or Wind Shift (see below).

Wind Direction Mode



The top pane of the display shows Wind direction.

Apparant Wind Speed (AWS), Apparant Wind Angle (AWA), Beaufort Wind Speed (BFT) and Heading (HDG) are available in the lower pane. The bar graph is disabled in this mode.

5.3 Depth Pop-up and Depth Shallow Alarm

To warn of shallow water, a depth pop-up and shallow water alarm can be configured in setup.

Depth Pop-up



When the depth is less than a pre-set value, the Depth page automatically replaces the data item displayed in the lower pane. The Depth page continues to be displayed until the depth increases above the preset level, when the original lower pane display is restored.

Depth Shallow Alarm



Sounds to indicate that the water depth has fallen below a preset level. The "bell" icon is displayed in the lower pane.

The depth value that triggers the alarm is affected by any keel or waterline offsets that have been added. See page 22 to set the alarm function. The alarm does not sound as the depth increases above the preset level.

5.4 Speed Trim

To allow visualisation of speed trends, a speed trim function is available. The Speed Trim bargraph shows the percentage difference between the current boat speed and a reference speed.



The Race Master automatically calculates the reference speed as the rolling average of the boat speed over the previous two minutes; this value is shown in the lower pane of the Speed

Trim (TriM) page.

If required, you can use the Speed Trim (TriM) page to lock the reference speed.

Pressing  captures the current boat speed as the reference for the trim function and the locked value is displayed.

Once locked the reference speed remains fixed until the Race Master is switched off.

5.5 Bar Graph Functionality

The bar graph can be configured in setup (see page 24) to show one of the data items described below. **Note:** in stand alone mode, Wind Shift is the only bar graph function available.

Wind Shift



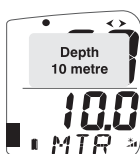
Upwind, wind shift is indicated using a fixed scale of +/- 25 degrees about a central zero.

Each segment of the graph corresponds to 2.5 degrees of shift.



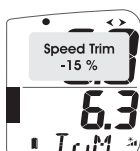
Downwind, the graph indicates the angle sailed relative to the Mean Wind Direction (MWD) from a zero at the bottom of the graph.

Each segment of the graph corresponds to 2.5 degrees of shift.



Depth

Depth is indicated using a fixed scale 0 to 20m with zero at the bottom of the graph. Each segment of the graph corresponds to 1m of depth. The bar graph always indicates depth in metres, even if other depth units are chosen for the digital display.



Speed Trim

Speed trim is indicated using a default scale of +/- 25 percent about a central zero. The scale can set between +/- 25 and +/- 100 percent in setup (see page 22).

5.6 Page Hiding

You may hide unwanted pages to configure the Race Master to your needs:

To select page hiding mode

Press and hold  to enter set up

Press  repeatedly to reach the OPT (Options) chapter

Press  repeatedly to reach the HiDE (Page Hiding) page

Press  to activate page hiding for 5 minutes

Press and hold  to exit setup.

To hide pages

Once page hiding is activated:

Use  and  to select a page to hide

Press  for 2 seconds to hide the currently visible page.

A period of 5 minutes is allowed during which you may hide pages.

If you have previously hidden pages and wish to return to all pages visible

Go to the setup OPT (Options) chapter (as above)

Press  repeatedly to reach the PAgE HID (Pages Hidden) page

Press  to restore all hidden pages

Press and hold  to exit setup.

5.7 Operation with Wind Data on the network

When Wind data is available on the network, operation of the Race Master wind and line bias functions is simplified.

Mean Wind Direction (MWD) is automatically calculated as an average of the true wind direction. The time period for the average can be configured in setup (see page 23).

The automatic value can be over-ridden at any time by pressing  in the Wind Shift (WND) page; the current true wind direction is captured and retained as the Mean Wind Direction (MWD); the MWD popup is shown to allow editing of the captured value Averaging is then disabled until the system is switched off.

The manual setup functions for Mean Wind Direction (MWD) and Tack Angle (TAK) are redundant and are disabled.

Line Bias (LineE) is captured as in section 3.3 (page 8). The Line Bias page permanently shows the bias angle and preferred end of the line; which are continually updated to reflect changes in the wind direction. Line Perpendicular is redundant and is not displayed.



6 Setup and Calibration

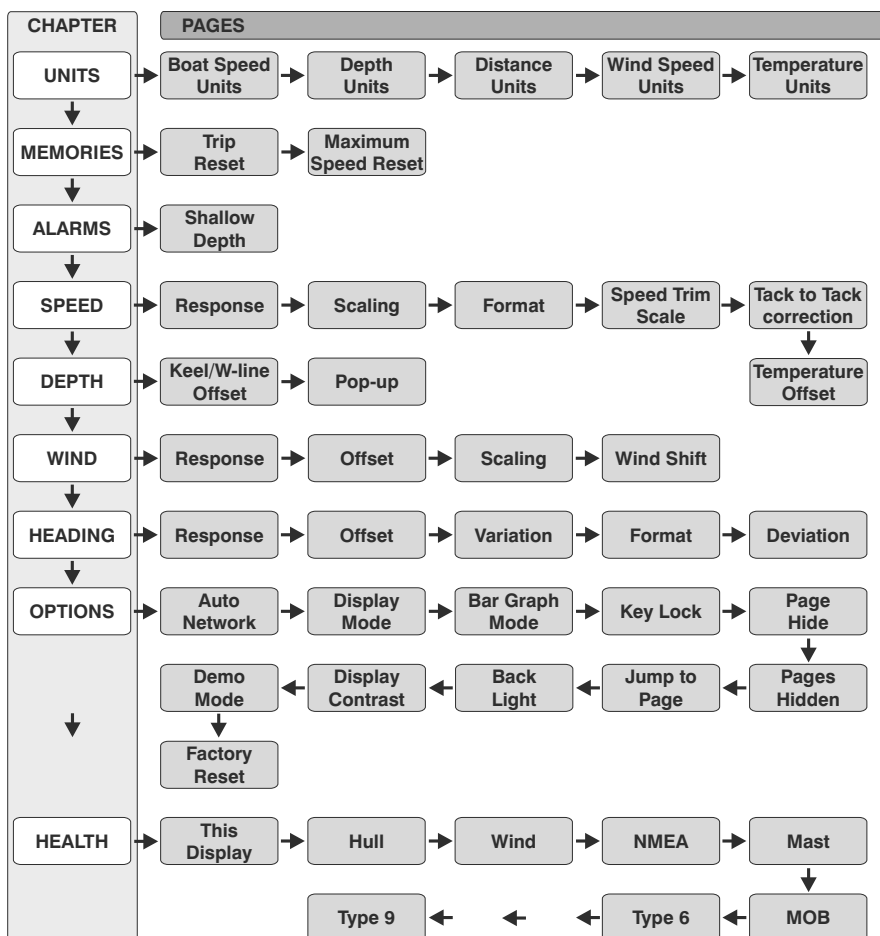
6.1 Setup and Calibration Organisation

Setup is organised into Chapters, each comprising a number of Pages. Setup pages use both the top and bottom panes of the display.

The diagram below shows the layout of the available chapters and pages.

In Micronet mode, setup is entered at the Units chapter.

For a full description of each setup page refer to section 6.4.



6.2 Setup and Calibration Operation

To enter Setup



Warning: It is not possible to enter setup mode while the Race Timer (TMR) or Wind Shift (WND) page is currently visible. Scroll to a different page in order to enter setup

Press and hold , the first chapter title page is displayed

To change the active chapter

Press  repeatedly until the desired chapter title page is displayed.

At the end of the chapter cycle, the display returns to the first chapter title page.

If you are currently on a chapter parameter page, you must return to the chapter title page before you can move to a new chapter.

To access the setup pages

Use  to scroll through the pages.  returns to the previous page.

6.3 Editing Setup Data

Parameter values may be one of four types:

A user editable numeric value (for example, the magnetic variation may have the value 03 degrees)

To edit a numeric parameter value:

Press . The value data will begin to flash.

Use  and  to adjust the value.

Press  again to set the new value.

A resetable numeric memory value (for example the average speed memory can be reset to the current speed)

To reset a memory value:

Press . The parameter is reset.

A list of options (for example, the heading response parameter may have the values SLO , mED or FAST).

To select a parameter option from a list:

Press . The parameter option will begin to flash.

Use  and  to select the option required.

Press  again to set the new option.

A toggle between two alternative options (for example the keylock parameter can be either ON or OFF)

To toggle between alternate parameter settings:

Press . The setting will toggle between the options.

6.4 Setup Parameter Descriptions

In the descriptions below, system default values are shown in **bold** text

Units Chapter



Speed Units

The units in which ALL speed related information is displayed. The options available are: **KTS (Knots)**, KPH (Kilometres per hour) or MPH (Statute Miles per hour).



Depth Units

The units in which ALL depth related information is displayed. The options available are: **FT (Feet)**, MTR (Metres) or FA (Fathoms).



Distance Units

Sets the units in which ALL Distance related information is displayed. The options available are: **NM (Nautical Miles)**, KM (Kilometres) or SM (Statute Miles).



Wind Speed Units

The units in which ALL wind speed related information is displayed. The options available are: **KTS (Knots)** or M/S (Metres per second).



Temperature Units

Sets the units in which water temperature information is displayed. The options available are: **°C (Degrees Celsius)** or °F (Degrees Fahrenheit).

Memories Chapter



Trip Distance

The distance travelled since the last Trip Reset. Resets to 0.0.



Maximum Speed

The maximum speed attained since switch on or since the last Maximum Speed Reset. Resets to current boat speed.

Alarms Chapter



Shallow Water Alarm

Sets the depth at which the display will signal the alarm.

The options are: **Off** and 0.5 to 25.0 feet (0.1 to 7.6 metres) (0.1 to 4.1 fathoms).

Values are displayed in the current units (see page 21)

Speed Chapter



Speed Response

Sets the update period of the Speed display.

The options are: **Auto (Automatic)**, SLO (Slow), mED (Medium), FAST (Fast).



Speed Calibration

A percentage factor that corrects the information from the paddlewheel.

See page 29 for the calibration procedure.



Speed Display Format

Sets the number of decimal places to which the boat speed information is displayed.

The options are **0.1** or 0.01.



Speed Trim Range

Sets the full scale display value of the speed trim bar graph.

The value can be set from 25 to 100 percent.

A value of 25% indicates that, at full screen, the boat speed is +/- 25% of the locked speed.



Tack to Tack correction

A value that corrects the speed displayed when the boat is on starboard tack, to take account of inherent differences of the measured speed on opposite tacks, e.g caused by off-centre installation of the transducer



Sea Temperature Calibration

A value that corrects the information from the temperature sensor

The live water temperature is shown in the top pane and the applied correction value (maximum +/- 10 degrees) in the bottom pane.

Depth Chapter



Keel / Waterline Offset

Allows a keel offset to be added allowing the display depth reading to indicate depth below the bottom of the boat, or a waterline offset allowing the depth reading to indicate actual water depth. See page 28 to set a depth offset.



Depth Pop-up threshold

Sets the threshold depth for the depth pop-up. When the depth falls below the set value, the depth screen replaces the normal display page. When set to zero, the depth popup is switched off.

Wind Chapter



Wind Response

Sets the update period of the wind display.

The options available are: **Auto (automatic)**, SLO (slow), mED (medium), FAST (fast).



Wind Angle Offset

Aligns the displayed apparent wind angle with the actual wind direction. See page 30 for the calibration process.

The live wind angle is shown in the top pane, with the tack shown as PRT or STB. The applied correction value is shown in the bottom pane (a negative offset is to port, positive is to starboard).



Wind Speed Calibration

A percentage factor which corrects the information from the wind speed sensor. See page 30 for the calibration process.

The live wind speed is shown in the lower pane, the applied correction percentage is shown in the upper pane).



Wind Shift averaging period

The period in minutes for the automatic averaging of true wind direction to calculate Mean Wind Direction (MWD). Default is 10 minutes.

Compass Chapter



Heading Response

Sets the update period of the compass display.

Auto (automatic), SLO (slow), mED (medium), FAST (fast)



Compass Offset

Aligns the displayed heading with the actual magnetic heading of the boat (see page 27 for the calibration process). The live heading is shown on the lower line of the bottom pane, with the applied offset on the upper line as +/- degrees (0 to +/- 180).



Magnetic Variation

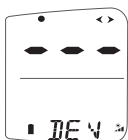
Allows manual entry of local magnetic variation. A value between W90 degrees and E90 degrees.

This setting is ignored if variation information is available from a GPS source.



Heading Format

The system can be configured to show heading information in either **MAG (Magnetic)** or **TRU (True)** format. Magnetic Variation must be set to enable True display format (see section above). A True Heading is indicated by the TRUE icon in the upper pane; the absence of this icon indicates a Magnetic heading.



Magnetic Deviation

Allows the compass to be corrected for the influence of magnetic objects in the boat. See page 27 for the calibration process.

On entry, the top pane shows the maximum deviation applied (dashes if the compass has not been corrected).

Options Chapter



Auto Networking

Adds display units or transducers to the Micronet network.

This function is only available on the display which was used to power up the system. Refer to the "Auto Network" sheet for further information. The Race Master is network locked by default. See the troubleshooting section if you have a problem introducing your Race Master to an existing network



Operating Mode

Configures the operating mode of the Micronet Race Master display. The options are **HDG (Heading)**, **Spd (Speed)** or **DIR (Wind Direction)**.

See page 16 for details of the operating modes.



Bar Graph Mode

Configures the bar graph for the current operating mode of the display.

The options are **SPd (speed trim)**, **dEP (depth)** or **Wind (Wind Shift)**.

In Speed mode the default is **SPd (speed trim)**, in Heading mode the default is **Wind (Wind Shift)**.



Key Lock

Press  to toggle between keylock **OFF** and On



Page Hiding

Enables the user to hide pages (see page 18 for the page hiding process). Note that a) the pages required for Standalone operation can not be hidden, b) Apparent Wind Speed (AWS) can not be hidden in Wind Direction Mode.



Pages Hidden/Unhide Pages

Displays the number of hidden pages. Page Hiding can be cleared, returning to all pages visible
See page 18 for the page unhiding process.



Auto Page

Chooses the page that will automatically be displayed at the end of the Timer countdown.

The options are: **WND (Wind Shift)**, SPD (Boat Speed), DEP (Depth) or HDG (Heading).



Backlight control

Configures the display to control the system backlighting or just its own backlighting.

The options are: **NWK (network)**, LOC (local).



Display Contrast

Adjusts the viewing angle of the LCD display to improve visibility under varied mounting possibilities.

Available values are: 1 - 7 **default 4**.



Demonstration Mode

Allows the display to show information when NOT installed as part of a Micronet system for demonstration purposes only.

The Race Master will return to default **OFF** on power down.



Factory Reset

Returns all settings to the factory default values.

Pressing  starts a three second countdown, at the end of which all values are returned to their defaults. The countdown can be stopped and reset cancelled by pressing  again.

Health Chapter



Status of the Race Master display

The software version is shown in the bottom pane. Battery level and charge rate are shown using the appropriate icons.

If the display was used to switch on the system, the number of items (nodes) in the system will be shown in the top pane; otherwise, signal strength is shown in the top pane.



Hull Transmitter status

Shows the signal strength, software version, battery level and charge rate of the Hull Transmitter to assist in trouble shooting and fault finding

Similar information pages are available for other transmitters if they are connected to the micronet network, for example:

Wind Transmitter (identified as WND)

Wireless (NMEA) Interface (NME)

Mast Rotation Transmitter (MST)

Man Overboard Transmitter (MOB)

7 Seatrial and Calibration

Once the Micronet system has been installed on the vessel and Auto Networking has been completed it is necessary to carry out Calibration. It is not safe to use the displays for navigational purposes until Calibration has been carried out correctly.

7.1 Compass Calibration and Alignment

To compensate for deviation caused by magnetic objects on the boat, it is necessary to carry out a deviation correction turn.

The compass reading may be set to the correct heading.

To begin the calibration process

Press and hold  for 2 seconds to enter Setup.

Press  repeatedly to scroll to the **Heading** chapter

To complete a deviation correction turn

Press  to scroll to the **DEV** page



Press  to enter Compass Calibration Mode

Turn the vessel slowly keeping the speed below 4 knots and taking approximately 2 minutes to complete 360 degrees. Keep turning the vessel until the display changes to show a value (usually about 1.25 turns)



Note: If the rate of turn of the vessel is too fast the display will show "FAST TRN". It is not necessary to abandon the turn at this stage but do lessen the rate of turn by reducing speed or widening the turning circle.

Press  to exit Compass Calibration Mode

Then, to align the heading

Using a hand bearing compass or an external fixed compass, steer the vessel on a known heading.

Warning: Only use an external fixed compass as a known heading if you are certain it has been checked and compensated.

Press  repeatedly to scroll to the **Compass Offset** page.



Press  to enter Edit Mode.

Use  and  to change the displayed heading (in small text) to the known correct value.



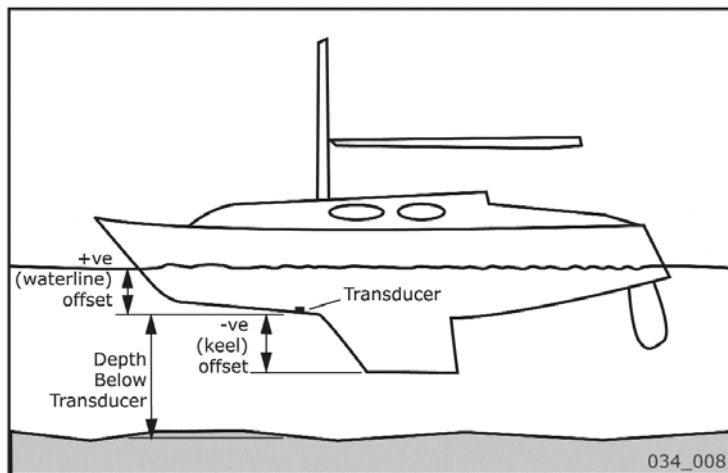
The display shows the offset entered.

Press  to exit Edit Mode.

Press and hold  to exit Setup and return to normal operation.

7.2 Depth Offset

The default depth offset is 0.0 making the display read the depth below the transducer. By adding a +ve or -ve offset the display will show the waterline depth or depth below the keel respectively.



To enter a depth offset:

Press and hold  to enter Setup

Press  repeatedly to scroll to the **Depth** chapter

Press  to scroll to the **Depth Offset** page



Press  to enter Edit Mode

Use  and  to change the value



Press  to exit Edit Mode

Press and hold  to exit Setup and return to normal operation.

7.3 Speed Calibration

To ensure that the boat speed (and distance) is accurate it is necessary to calibrate the speed to take into account variations in water flow between different hulls. Adjustment is made by multiplying the speed through the water (V) by a percentage calibration factor.

It is essential to carry out this procedure at a time when little or no tide is flowing.

To take account of tidal flow, the calibration run should be carried out twice, once with the tide and once against the tide. The calibration percentage factor should then be set to the average of the factors determined by the two runs.

To enter a Speed Calibration Factor:

With the vessel under power, steer a straight course and allow the boat speed reading to settle to a constant value. Check the GPS is showing a constant SOG.

Press and hold  to enter Setup

Press  repeatedly to scroll to the **Speed** chapter

Press  repeatedly to scroll to the **Speed Calibration** page



Press  to enter Edit Mode

Use  and  to change the displayed % value until the speed reading shown (in small text) matches the SOG from the GPS.



Press  to exit Edit Mode

Press and hold  to exit Setup and return to normal operation.

Should you be unable to carry out this procedure due to strong tidal conditions or poor GPS information there is further information regarding Speed Calibration using a measured distance on the Raymarine website at www.raymarine.com.

7.4 Wind Calibration

Both Wind Speed and Direction can be calibrated to ensure that readings from the Wind Transmitter are displayed accurately.

Wind Angle Offset

Motor the vessel directly into the wind.

Press and hold  to enter Setup

Press  repeatedly to scroll to the **Wind** chapter



Press  repeatedly to scroll to the **Wind Offset** page

Press  to enter Edit Mode

Press  and  to change the wind angle displayed in the upper pane to 000.



The display will indicate the number of degrees of offset entered.

Press  to exit Edit Mode

Press and hold  to exit Setup and return to normal operation.

Wind Speed Correction

Note: The Wind Speed reading is factory calibrated to display correctly and should not be altered unless external factors are thought to be causing incorrect readings. Correction should only be carried out if a known correct Wind Speed is available.

Press and hold  to enter Setup

Press  repeatedly to scroll to the **Wind** chapter

Press  repeatedly to select the **Wind Calibration** page



Press  to enter Edit Mode

Use  and  to change the value displayed in the bottom line of the lower pane to the required percentage.



The live wind speed is displayed in the top row of the lower pane.

Press  to exit Edit Mode

Press and hold  to exit Setup and return to normal operation.

8 Installation



Warning: The Race Master must be mounted within 20 degrees of the vertical to permit correct functioning of the integrated compass sensor.

Ideally, the display should be mounted at or below eye height; if this is not possible it may be necessary to adjust the display contrast to optimise visibility (see page 25).

Select a mounting location that is as far as possible from magnetic objects that might interfere with the compass sensor.

Attach the Cradle to a suitable bracket or bulkhead using the bolts or screws supplied. Take care to ensure the plane of the cradle is at right angles to the centreline of the vessel, minor mis-alignment may be corrected by following the Calibration process (see page 27).

See the Raymarine website (www.raymarine.com) for details of the mounting bracket options available for the Race Master.



For installation of the Solar Panel and the Hull Transmitter and Transducer, see the separately supplied Installation Guides.

9 Maintenance and Fault Finding

9.1 Care and Maintenance

All Micronet products are totally sealed against water and are not serviceable. Any attempt to take a Micronet product apart will invalidate the warranty.

To clean, use only a damp, soft cloth. No detergents, solvents or abrasives should be used. To avoid damaging a Micronet display unit we recommend storing in the supplied soft pack when not in use.

If the displays are to be stored for a long period before next use (e.g. over winter) ensure that the batteries are fully charged before storage.

9.2 Fault Finding

The No Power alarm sounds



Check the Hull Transmitter connection to the solar panel. If this connection is not made, then you will see the No Power alarm 10 seconds after powering up your system. The Solar Panel is sufficient to power the Hull Transmitter (and the Wireless (NMEA) Interface if used).

The Race Master battery symbol flashes and the unit switches off.

The Race Master battery level is low. Leave the Race Master in bright sunlight for 12 hours minimum to recharge the internal battery.

Low Battery Alarm sounds.



Check the battery level of the Hull Transmitter by going to Setup and scrolling to the Health Chapter. The battery level icon of the HUL page should show 1, 2 or 3 bars to ensure correct operation. Check that the Solar Panel is correctly connected to the Hull Transmitter.

Note: a low battery alarm can also be caused by a Wireless (NMEA) Interface or Wind Transmitter if these are in use with the system. Ensure that these transmitters are fully charged if required.

Data is shown as dashes.

The information is not being transmitted to the Race Master. Enter Setup and scroll to the Health Chapter. Check the signal levels of the transmitters. The signal level should show a value of greater than 3 to ensure correct operation.

Compass Transducer rattles and/or splashes

This is normal. The fluxgate compass is gimbaled in a fluid filled container to ensure it is not affected by the boats movement in the water.

The heading displayed does not agree with the expected heading

Ensure that the Race Master is mounted correctly, it must be mounted within 20 degrees of the vertical.

There may be magnetic objects within 70cm (2 ft) of the Race Master. Remove magnetic objects or carry out the compass calibration procedure (see section 17).

The Bar Graph does not correctly indicate headers/lifts

The Race Master has not been setup correctly. Ensure that Mean Wind Direction (MWD) and Tack Angle (TA) have been setup (see section 3.3 and section 4).

Boat Speed reads 0

Information being transmitted from the Hull Transmitter is being received with a zero value. Check the paddle wheel for fouling, clean it and make sure it turns easily.

Wind Speed reads 0

Information being transmitted from the Wind Transmitter is being received with a zero value. If the anemometer cups at the top of the mast are turning and the wind speed reads zero then there is a problem with your Wind Transmitter.

No NMEA data showing on external displays

Enter Setup and Calibration Mode, scroll to the Health Chapter and check the signal level and battery status of the Wireless (NMEA) Interface. If the signal level shows a value of greater than 3 then check the data connections and the settings of the NMEA source equipment to ensure that NMEA 0183 data is being transmitted correctly.

The Depth Alarm does not sound

If the actual water depth is shallow and the alarm has not sounded it is most likely that the alarm is switched off. Enter Setup and Calibration Mode and scroll through to the Depth Chapter. Ensure the Depth Alarm settings are correct.

Autonetworking fails to detect a Race Master Display

The Race Master autonetwork function is locked by default. To unlock the function: power on the Race master, go to Setup and scroll to the Options chapter, Autonetwork Page. Press  to start the countdown. When the countdown is complete, press  again to exit the Autonetworking function. The Race Master autonetwork function is now unlocked. Try again to introduce your Race Master to your network.

Appendix A - Specifications

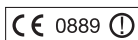
Height of digits:	27mm (upper pane), 18mm (lower pane)
Backlighting:	3 levels with daylight shutoff System-wide or local control
Power:	Solar Powered 300 hrs autonomy by day, 7 nights at brightest backlighting, 20 nights at economy backlighting without charge
Units of display:	Boat Speed (knots, kilometres per hour, statute miles per hour) Distance (nautical miles, statute miles, kilometres) Depth (metres, feet, fathoms) Wind Speed (knots, metres per second, Beaufort)
Alarm:	Audible Alarm for Depth
Weight:	435g (1 lb)
Operating Temp:	-10 ^o to +60 ^o C (14 ^o to 140 ^o F)
Frequency:	868 MHz or 916 MHz

Warranty Information

For warranty details for this product see the Raymarine website at www.raymarine.com/warranty.

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions. (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference's that may cause undesirable operation.

Note: the manufacturer is not responsible for any radio or TV interference caused by unauthorized modifications to this equipment. Such modifications could void the user's authority to operate the equipment.



Raymarine Ltd hereby declare that the Micronet Digital Display is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC.



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